

# Medium Access Control

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# Roadmap

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- Overview
- Wireless MAC protocols
  - Carrier Sense Multiple Access
  - Multiple Access with Collision Avoidance (MACA) and MACAW
  - MACA By Invitation
  - IEEE 802.11
  - IEEE 802.15.4 and ZigBee
- Contention-Free MAC Protocols
- Contention-Based MAC Protocols
- Hybrid MAC Protocols

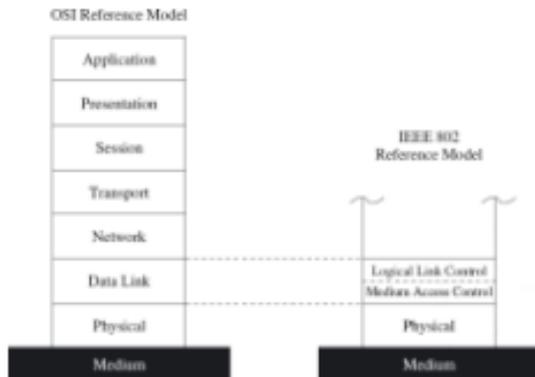
# Medium Access Control

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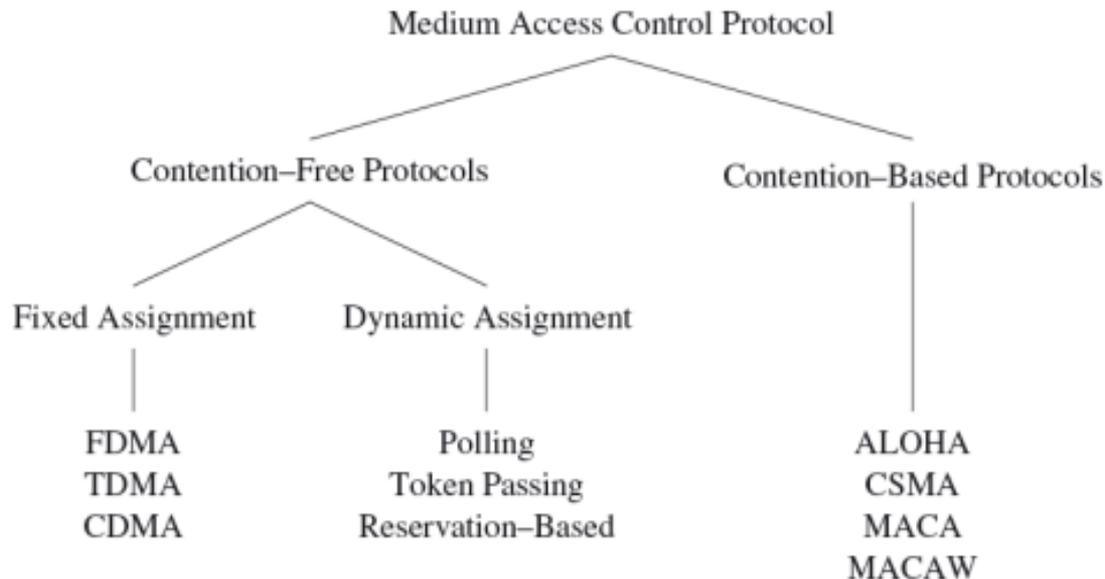
- In most networks, multiple nodes **share a communication medium** for transmitting their data packets
- The **medium access control (MAC)** protocol is primarily responsible for regulating access to the shared medium
- The choice of MAC protocol has a direct bearing on the reliability and efficiency of network transmissions
  - due to errors and interferences in wireless communications and to other challenges
- **Energy efficiency** also affects the design of the MAC protocol
  - trade energy efficiency for increased latency or a reduction in throughput or fairness

# Overview

- Responsibilities of MAC layer include:
  - decide when a node accesses a shared medium
  - resolve any potential conflicts between competing nodes
  - correct communication errors occurring at the physical layer
  - perform other activities such as framing, addressing, and flow control
- Second layer of the OSI reference model (**data link layer**) or the IEEE 802 reference model (which divides data link layer into **logical link control** and **medium access control** layer)



# MAC Protocol Categorization



# Contention-Free Medium Access

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- Collisions can be avoided by ensuring that each node can use its allocated resources exclusively
- Examples of fixed assignment strategies:
  - **FDMA**: Frequency Division Multiple Access
    - ▶ the frequency band is divided into several smaller frequency bands
    - ▶ the data transfer between a pair of nodes uses one frequency band
    - ▶ all other nodes use a different frequency band
  - **TDMA**: Time Division Multiple Access
    - ▶ multiple devices to use the same frequency band
    - ▶ relies on periodic time windows (**frames**)
      - frames consist of a fixed number of transmission slots to separate the medium accesses of different devices
      - a time **schedule** indicates which node may transmit data during a certain slot

# Contention-Free Medium Access

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- Examples of fixed assignment strategies (contd.):
  - **CDMA**: Code Division Multiple Access
    - ▶ simultaneous accesses of the wireless medium are supported using different **codes**
    - ▶ if these codes are **orthogonal**, it is possible for multiple communications to share the same frequency band
    - ▶ **forward error correction** (FEC) at the receiver is used to recover from interferences among these simultaneous communications
  - Fixed assignment strategies are **inefficient**
    - it is **impossible to reallocate** slots belonging to one device to other devices if not needed in every frame
      - ▶ generating schedules for an entire network can be a daunting task
      - ▶ these schedules may require modifications every time the network topology or traffic characteristics in the network change

# Contention-Free Medium Access

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- └ Dynamic assignment strategies: allow nodes to access the medium **on demand**
  - **polling-based protocols**
    - ▶ a controller device issues small polling frames in a round-robin fashion, asking each station if it has data to send
    - ▶ if no data to be sent, the controller polls the next station
  - **token passing**
    - ▶ stations pass a polling request to each other (round-robin fashion) using a special frame called a token
    - ▶ a station is allowed to transmit data only when it holds the token
- └ **reservation-based protocols**
  - ▶ static time slots used to reserve future access to the medium
  - ▶ e.g., a node can indicate its desire to transmit data by toggling a reservation bit in a fixed location
  - ▶ these often very complex protocols then ensure that other potentially conflicting nodes take note of such a reservation to avoid collisions

# Contention-Based Medium Access

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- Nodes may initiate transmissions at the same time
  - requires mechanisms to reduce the number of collisions and to recover from collisions
- Example 1: **ALOHA** protocol
  - uses acknowledgments to confirm the success of a broadcast data transmission
    - ▶ allows nodes to access the medium immediately
    - ▶ addresses collisions with approaches such as **exponential back-off** to increase the likelihood of successful transmissions
- Example 2: **slotted-ALOHA** protocol
  - requires that a station may commence transmission only at predefined points in time (the beginning of a time slot)
  - increases the efficiency of ALOHA
  - introduces the need for synchronization among nodes

# Contention-Based Medium Access

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- Carrier Sense Multiple Access (CSMA)
  - CSMA with Collision Detection (CSMA/CD)
    - ▶ sender first senses the medium to determine whether it is idle or busy
      - if it is found busy, the sender refrains from transmitting packets
      - if the medium is idle, the sender can initiate data transmission
  - CSMA with Collision Avoidance (CSMA/CA)
    - ▶ CSMA/CD requires that sender aware of collisions
    - ▶ instead, CSMA/CA attempts to avoid collisions in the first place

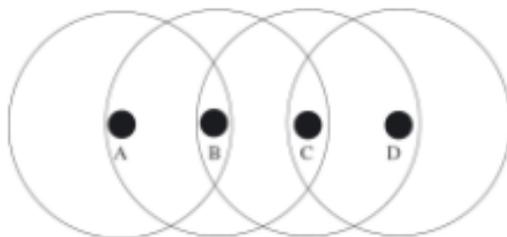
# Hidden and Exposed Terminal Problems

## Hidden-terminal problem

- senders A and C are able to reach B, but cannot overhear each other's signals
- it is possible for A and C to transmit data to B at the same time, causing a collision at B, without being able to directly detect this collision

## Exposed-terminal problem

- C wants to transmit data D, but decides to wait because it overhears an ongoing transmission from B to A
- B's transmission could not interfere with data reception at C



# Carrier Sense Multiple Access

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- Nodes first sense the medium before they begin a transmission (reduces number of collisions)
- Non-persistent CSMA
  - node is allowed to immediately transmit data once medium is idle
  - if the medium is busy, the node performs a back-off operation
    - ▶ wait for a certain amount of time before attempting to transmit again
- 1-persistent CSMA
  - node wishing to transmit data continuously senses the medium for activity
  - once the medium is found idle, the node transmits data immediately
  - if a collision occurs, the node waits for a random period of time before attempting to transmit again

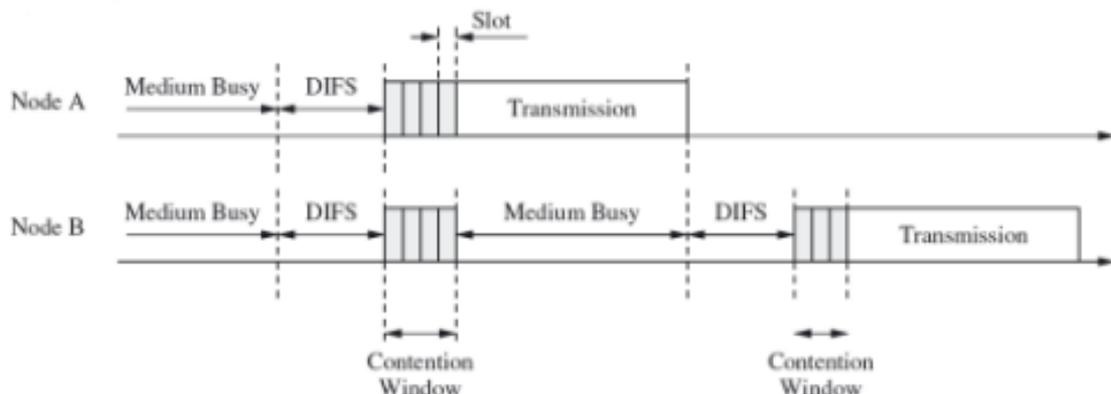
# Carrier Sense Multiple Access

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- **p-persistent CSMA**
  - node continuously senses the medium
  - node transmits data with a probability  $p$  once the medium becomes idle
  - delays transmission with a probability  $1 - p$
  - random back-off values are either continuous values in the case of un-slotted CSMA or multiples of a fixed slot size in slotted CSMA
- **CSMA/CA (CSMA with Collision Avoidance)**
  - nodes sense the medium, but do not immediately access the channel when it is found idle
  - instead, a node waits for a time period called **DCF interframe space (DIFS)** plus a multiple of a slot size
  - in case there are multiple nodes attempting to access the medium, the one with the shorter back-off period will win

# Carrier Sense Multiple Access

- Example:
  - node A waits for  $DIFS + 4 * s$  (where  $s$  represents the slot size), while node B's back-off is  $DIFS + 7 * s$
  - once node A begins with its transmission, node B freezes its own back-off timer and resumes the timer after node A completes its transmission plus another period of DIFS
  - once node B's back-off timer expires, it can also begin its transmission



# MACA and MACAW

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- Multiple Access with Collision Avoidance (MACA)
  - dynamic reservation mechanism
  - sender indicates desire to send with **ready-to-send (RTS)** packet
  - intended receiver responds with **clear-to-send (CTS)** packet
  - if sender does not receive CTS, it will retry at later point in time
  - nodes overhearing RTS or CTS know that reservation has taken place and must wait (e.g., based on the size of data transmission)
  - address hidden terminal problem and reduces number of collisions
- MACA for Wireless LANs (MACAW)
  - receiver responds with acknowledgment (ACK) after data reception
    - ▶ other nodes in receiver's range learn that channel is available
  - nodes hearing RTS, but not CTS do not know if transmission will occur
    - ▶ MACAW uses **data sending (DS)** packet, sent by sender after receiving CTS to inform such nodes of successful handshake

# MACA By Invitation

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- In MACA-BI, destination device initiates data transfers by sending a **Ready To Receive (RTR)** packet to the source
  - source then responds with the data message
- Compared to MACA, MACA-BI reduces overhead
  - increases the theoretical maximum throughput
  - depends on the destination knowing when to receive data
- Source nodes can use an optional field within the data message to indicate the number of queued messages
  - providing the destination with an indication that more RTS packets will be required

# IEEE 802.11

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- Published in 1999 by the [Institute of Electrical and Electronics Engineers \(IEEE\)](#)
  - specifies the physical and data link layers of the OSI model for wireless connections
- Often referred to as [Wireless Fidelity \(Wi-Fi\)](#)
  - certification given by [Wi-Fi Alliance](#), a group that ensures compatibility between hardware devices that use the 802.11 standard
- Wi-Fi combines concepts found in CSMA/CA and MACAW, but also offers features to preserve energy
- Two modes of operation
  - [Point Coordination Function \(PCF\)](#) mode
    - ▶ communication among devices goes through a central entity called an [access point \(AP\)](#) or [base station \(BS\)](#): [managed mode](#)
  - [Distributed Coordination Function \(DCF\)](#) mode
    - ▶ devices communicate directly with each other: [ad-hoc mode](#)

# IEEE 802.11

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- IEEE 802.11 is based on CSMA/CA
  - before a node transmits, it first senses the medium for activity
  - the node is allowed to transmit, if the medium is idle for at least a time period called the **DCF interframe space (DIFS)**
  - otherwise the device executes a **back-off algorithm** to defer transmission to a later time
  - this algorithm randomly selects a number of time slots to wait and stores this value in a back-off counter
  - for every time slot that passes without activity on the network, the counter is decremented and the device can attempt transmission when this counter reaches zero
  - if activity is detected before the counter reaches zero, the device waits until the channel has been idle for a period of DIFS before it continues to decrement the counter value

# IEEE 802.11

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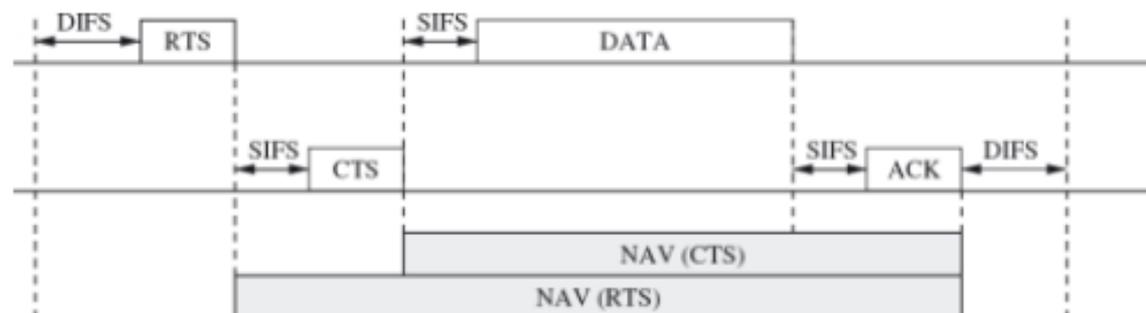
- After a successful transmission
  - receiver device responds with an acknowledgment after waiting for a time period called the **short interframe space (SIFS)**
  - the value of SIFS is smaller than the value of DIFS to ensure that no other device accesses the channel before the receiver can transmit its acknowledgment
- Once a node A makes a reservation using RTS and CTS control messages
  - another neighboring node B, overhearing the RTS message, must refrain from accessing the medium until node A's transmission has been completed and acknowledged
  - however, this would mean that node B has to continuously sense the medium to detect when it becomes idle again

# IEEE 802.11

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- Instead, A's RTS message carries the size of the data it will transmit
  - allowing node B to estimate how long the transmission will take and to decide whether to enter a low-power sleep mode
  - some neighboring nodes may only overhear CTS (but not RTS), therefore, the data size is also carried in the CTS message
  - using the data size information, neighboring nodes set a **network allocation vector (NAV)** that indicates how long the medium will be unavailable
    - ▶ reduces the need for continuously sensing the medium, allowing a node to **save power**

# IEEE 802.11



# IEEE 802.11

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- PCF mode
  - access point (AP) coordinates channel access to ensure collision-free communication
    - ▶ periodically broadcasts a beacon to its client devices (includes list of devices with data pending at AP)
  - during contention-free period, AP transmits these packets to its client devices
  - AP can also poll client devices to allow them to initiate data transfers
  - AP uses a wait period called the **PCF interframe space (PIFS)**
    - ▶ PIFS is shorter than DIFS, but longer than SIFS
    - ▶ ensures that PCF traffic has priority over traffic generated by devices operating in the DCF mode, without interfering with control messages in the DCF mode such as CTS and ACK

# IEEE 802.11

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- Focus of IEEE 802.11 is on providing **fair access** to the medium with support for high throughput and mobility
  - since devices spend a large amount of time listening to the medium and collisions occur frequently, this standard incurs large overheads, including significant energy costs
- Energy consumption problem
  - IEEE 802.11 offers a **power saving mode (PSM)** for devices operating in the PCF mode
  - devices can inform the AP that they wish to enter a low-power sleep mode using special control messages
  - these devices wake up periodically to receive beacon messages from the AP to determine if they should stay awake to receive incoming messages
  - saves energy, but only works in the infrastructure mode and it is not specified when or how long devices should sleep

# IEEE 802.15.4

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- IEEE 802.15.4
  - created for low-power devices in the 868 MHz, 915 MHz, and 2.45 GHz frequency bands
  - supports two **transmission modes**:
    - ▶ **UWB PHY**
      - bit rates: 110 kbps, 851 kbps (nominal), 6.81 kbps, and 27.24 Mbps
    - ▶ **CSS PHY**
      - bit rates: 1 Mbps (nominal) and 250 kbps

# ZigBee

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- Before 802.15.4, [ZigBee Alliance](#) worked on low-cost communication technology for low data rates and low power consumption
- IEEE and ZigBee Alliance joined forces and ZigBee has become the commercial name for the IEEE 802.15.4 technology
- [Star](#) mode:
  - communication via the [Personal Area Network \(PAN\)](#) coordinator
  - [synchronized](#) mode (beacon-enabled)
    - ▶ PAN coordinator periodically broadcasts beacons for synchronization and management
    - ▶ slotted channel access: device performs random backoff before channel is sensed
      - if no activity, node waits until next slot and senses channel again until no activity has been detected for two consecutive slots
      - if activity, backoff procedure is repeated
  - [unsynchronized](#) mode: device access channel immediately when no activity is detected during the first initial backoff time

# ZigBee

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- Peer-to-peer mode:
  - devices are free to communicate directly with each other
  - but they still must associate with the PAN coordinator before they can participate in peer-to-peer communication
- Data transfer between the device and its PAN coordinator is **always initiated by the device**
  - allows a device to determine when data is transferred and to maximize its energy savings
    - ▶ when a device wants to send data to the PAN coordinator, it can use the previously described channel access method
    - ▶ the PAN coordinator transmits data intended for a device only after the device explicitly requested such a transmission
  - in both cases, optional acknowledgments can be used to let the PAN coordinator or device know that the transmission was successful

# IEEE 802.15.4 and ZigBee

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- Challenges:
  - standard does not clearly define the operation of the peer-to-peer approach
  - in large WSNs, it is unlikely that all devices will be able to use the same PAN coordinator
  - standard does allow communication among PAN coordinators, but this again is not well defined

# Contention-Free MAC Protocols

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- Concept:
  - allow only one sensor node to access the channel at any given time
  - thereby avoiding collisions and message retransmissions
  - assuming a perfect medium and environment
    - ▶ i.e., no other competing networks or misbehaving devices exist that could otherwise cause collisions or even jam a channel
- Contention-free protocols allocate resources to individual nodes to ensure exclusive resource access by only one node at any given time
- Exposes a number of desirable **characteristics**
  - node knows exactly when it has to turn on its radio
  - during all other times, radio can be turned off to preserve energy
  - fixed slot allocations impose upper bounds on delay
  - difficult to design schedules for large networks
  - difficult to handle changes in topology, density, traffic load

# Traffic-Adaptive Medium Access

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- TRAMA is an example of a contention-free MAC protocol with the goal to increase network throughput and energy efficiency (compared to TDMA)
- It uses a **distributed election scheme** to determine when nodes are allowed to transmit
  - based on information about the traffic at each node
  - avoids assigning slots to nodes with no traffic to send (increased throughput)
  - allows nodes to determine when they can become idle and do not have to listen to the channel (increased energy efficiency)

# Traffic-Adaptive Medium Access

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- TRAMA assumes a time-slotted channel, where time is divided into:
  - **periodic random-access intervals** (signaling slots)
  - **scheduled-access intervals** (transmission slots)
- **Random-access intervals**
  - **Neighbor Protocol (NP)** is used to propagate one-hop neighbor information among neighboring nodes
    - ▶ nodes join a network by transmitting during a randomly selected slot
    - ▶ packets transmitted during these slots are used to gather neighborhood information by carrying a set of added and deleted neighbors
    - ▶ in case no changes have occurred, these packets serve as “keep-alive” beacons
  - NP allows nodes to obtain consistent two-hop topology information

# Traffic-Adaptive Medium Access

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- Random-access intervals (contd.)
  - Schedule Exchange Protocol (SEP) establishes and broadcasts actual schedules (i.e., allocations of slots to a node)
    - ▶ each node computes a duration `SCHEDULE_INTERVAL`
      - represents the number of slots for which the node can announce its schedule to its neighbors
      - this duration depends on the rate at which the node's applications can produce packets
    - ▶ at time  $t$ , the node then computes the number of slots within  $[t, t + \text{SCHEDULE\_INTERVAL}]$  for which it has the highest priority among its two-hop neighbors
    - ▶ the node announces the selected slots and the intended receivers using a `schedule packet`
    - ▶ the last slot in this schedule is used to announce the next schedule for the next interval

# Traffic-Adaptive Medium Access

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- Random-access intervals (contd.)
  - Schedule Exchange Protocol (SEP) (contd.)
    - ▶ example:
      - a node's `SCHEDULE_INTERVAL` is 100 slots
      - the current time (slot number) is 1000
      - a possible slot selection for interval [1000, 1100] for this node could be 1011, 1021, 1049, 1050, and 1093
      - during slot 1093, the node broadcasts its new schedule for interval [1093, 1193]
    - ▶ list of intended receivers in the schedule packet is implemented as a `bitmap`
      - length of a bitmap is equal to the number of one-hop neighbors
        - » each bit in the bitmap corresponds to one particular receiver ordered by its identities
        - » every node can determine the receiver address based on the bitmap and its list of neighbors

# Traffic-Adaptive Medium Access

## □ Random-access intervals (contd.)

### □ Schedule Exchange Protocol (SEP) (contd.)

- ▶ slot selection is based on the node's priority at time  $t$ 
  - uses a pseudo-random hash of the concatenation of the node's identity  $i$  and  $t$ :
$$prio(i,t) = hash(i \oplus t)$$
  - node can indicate which slots it gives up, allowing other nodes to claim these unused slots
- ▶ a node can determine its state for any given time slot  $t$  based on its two-hop neighborhood information and the announced schedules
  - node  $i$  is in the **transmit (TX) state** if it has the highest priority and if it has data to send
  - node  $i$  is in the **receive (RX) state** if it is the intended receiver of the transmitter during slot  $t$
  - otherwise, the node can be switched into the **sleep (SL) state**

# Traffic-Adaptive Medium Access

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- Summary
  - compared to CSMA-based protocols
    - ▶ reduces the probability of collisions
    - ▶ increases the sleep time and energy savings
  - unlike standard TDMA approaches
    - ▶ TRAMA divides time into random-access and scheduled-access intervals
    - ▶ during the random-access intervals
      - nodes are awake to either transmit or receive topology information
      - the length of the random-access interval affects the overall duty cycle and achievable energy savings of a node

# Y-MAC

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- Y-MAC uses TDMA-based medium access but for multiple channels
- Divides time into **frames** and **slots**
  - each frame contains a broadcast period and a unicast period
  - every node must wake up at the beginning of a broadcast period
  - nodes contend for access to the medium during this period
    - ▶ if there are no incoming broadcast messages, each node turns off its radio awaiting its first assigned slot in the unicast period
    - ▶ each slot in the unicast period is assigned to only one node for receiving data
- Y-MAC uses a **receiver-driven model**
  - can be more energy-efficient under light traffic conditions, because each node samples the medium only in its own receive time slots
  - particularly important for radio transceivers, where the energy costs for receiving are greater than for transmitting (e.g., due to sophisticated despreading and error correction techniques)